

Second-Order Horizontal Synchrosqueezing of the S-transform: a Specific Wavelet Case Study

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Goals

- Computing efficient representations for handling non-stationary multicomponent signals
- Dealing with impulsive-like and/or strongly amplitude- and frequency-modulated signals
- Reversible representation allowing an extraction of the elementary deterministic signal components
- Link with the wavelet theory extending our previous work on the time-reassigned synchrosqueezed STFT [Fourer,Auger,2019]

 \Rightarrow **Proposed approach:** Time-frequency analysis combined with reassignment-based post-processing methods to improve the readability

Context: the French ANR ASCETE project (ANR-19-CE48-0001): 2019-2023

ASCETE: Analysis and Separation of Complex Signal: Exploiting the Time-Frequency Structure



Project holder: Dr. Sylvain Meignen (LJK, Grenoble, France)

Goals:

- Extends to previous methods (developed in ASTRES project)
- Combines deterministic signal processing methods with stochastic models
- New applications to audio, biomedicine, astrophysics, etc.

https://www-ljk.imag.fr/ASCETE/

Content



2 Time-Reassigned Synchrosqueezed S-transform

- Reassignment and synchrosqueezing
- Second-order time-reassigned synchrosqueezed S-transform

3 Numerical Results

- Time-frequency representations
- Signal reconstruction



The S-transform [Stockwell et al., 1996]

Generalization of the Short-Time Fourier Transform (STFT) using a frequency-dependent analysis window.

Definition

The S-transform of a zero-mean signal x is defined for a central frequency $\omega_0 > 0$ at any time t and radial frequency ω as:

$$\mathsf{ST}_{x}^{h}(t,\omega) = \frac{|\omega|}{\omega_{0}} \int_{-\infty}^{+\infty} x(\tau) h\left(\frac{\omega}{\omega_{0}}(t-\tau)\right)^{*} \mathbf{e}^{-j\omega\tau} d\tau \tag{1}$$

with $j^2 = -1$ and z^* the complex conjugate of z.

h is chosen as a Gaussian window with time-spread parameter T:

$$h(t) = g(t, T) = \frac{1}{\sqrt{2\pi}T} e^{-\frac{t^2}{2T^2}}$$
, which leads us to:

$$\mathsf{ST}_x^g(t,\omega) = \frac{|\omega|}{\omega_0} \int_{-\infty}^{+\infty} x(\tau) g\left(\frac{|\omega|}{\omega_0}(t-\tau), T\right)^* \mathbf{e}^{-j\omega\tau} \, d\tau \tag{2}$$

$$= \mathbf{e}^{-j\omega t} \int_{-\infty}^{+\infty} x(t+\tau) g\left(-\tau, \frac{\omega_0 T}{|\omega|}\right)^* \mathbf{e}^{-j\omega\tau} d\tau \qquad (3)$$

Link with the Continuous Wavelet Transform (CWT)

The CWT of a signal x at each time t and scale s for an admissible mother wavelet Ψ (*i.e.* satisfying $C_{\Psi} = \int_{\mathbb{R}} |F_{\Psi}(\omega)|^2 \frac{d\omega}{|\omega|} < +\infty$, with $F_x(\omega) = \int_{-\infty}^{+\infty} x(t) e^{-j\omega t} dt$) is:

$$W_{x}(t,s) = \frac{1}{\sqrt{|s|}} \int_{-\infty}^{+\infty} x(\tau) \Psi\left(\frac{\tau-t}{s}\right)^{*} d\tau$$
(4)

If we define $s = \frac{\omega_0}{\omega}$, Eq. (4) can be expressed as as:

$$CW_{x}(t,\omega) = \sqrt{\frac{|\omega|}{\omega_{0}}} \int_{-\infty}^{+\infty} x(\tau) \Psi\left(\frac{\omega}{\omega_{0}}(\tau-t)\right)^{*} d\tau.$$
(5)

The Morlet mother wavelet $\Psi(t) = \frac{\pi^{-1/4}}{\sqrt{T}} e^{\frac{-t^2}{2T^2}} e^{j\omega_0 t}$ leads to:

$$\mathsf{MW}_{\mathsf{x}}(t,\omega) = \sqrt{\frac{|\omega|}{\omega_0 T \sqrt{\pi}}} \int_{-\infty}^{+\infty} \mathsf{x}(\tau) \, \mathbf{e}^{-\frac{\omega^2 (t-\tau)^2}{2(\omega_0 T)^2}} \, \mathbf{e}^{-j\omega(\tau-t)} \, d\tau \tag{6}$$

$$=\sqrt{\frac{2\sqrt{\pi\omega_0}T}{|\omega|}}\,\mathbf{e}^{j\omega t}\mathsf{ST}_x^g(t,\omega)\tag{7}$$

The S-transform can be viewed as a specific (rescaled) continuous wavelet transform

$$ST_{x}^{g}(t,\omega) = \sqrt{\frac{|\omega|}{2\sqrt{\pi\omega_{0}T}}} e^{-j\omega t} MW_{x}(t,\omega)$$
(8)

S-transform marginalization and inversion formula 1/2

Using the frequency domain expression of the S-transform $ST_x(t,\omega) = \int_{-\infty}^{+\infty} F_x(\Omega+\omega) F_h\left(\frac{\omega_0}{\omega}\Omega\right) \, \mathbf{e}^{j\Omega t} \, \frac{d\Omega}{2\pi}$

Marginalization with respect to frequency

$$\int_{-\infty}^{+\infty} ST_{x}(t,\omega) \mathbf{e}^{j\omega t} \frac{d\omega}{|\omega|} = \iint_{\mathbb{R}^{2}} F_{x}(\omega+\Omega) F_{h}\left(\frac{\omega_{0}}{\omega}\Omega\right) \mathbf{e}^{j(\omega+\Omega)t} \frac{d\Omega}{2\pi} \frac{d\omega}{|\omega|}$$
(9)
$$= \iint_{\mathbb{R}^{2}} F_{x}(\Omega') \mathbf{e}^{j\Omega't} F_{h}\left(\xi-\omega_{0}\right) \left(\frac{|\omega_{0}\Omega'|}{\xi^{2}} \frac{|\xi|}{|\omega_{0}\Omega'|}\right) \frac{d\Omega'}{2\pi} d\xi$$
(10)
$$= \int_{-\infty}^{+\infty} F_{x}(\Omega') \mathbf{e}^{j\Omega't} \frac{d\Omega'}{2\pi} \cdot \int_{-\infty}^{+\infty} F_{h}(\xi-\omega_{0}) \frac{d\xi}{|\xi|}$$
(11)
$$= x(t) \cdot C_{h}(\omega_{0}T)$$
(12)

x can be recovered from ST_x using the synthesis formula

$$x(t) = \frac{1}{C_h(\omega_0 T)} \int_{-\infty}^{+\infty} ST_x(t,\omega) e^{j\omega t} \frac{d\omega}{|\omega|}$$
(13)

with $C_h(\omega_0 T) = \int_{-\infty}^{+\infty} e^{-\frac{(x-\omega_0 T)^2}{2}} \frac{dx}{|x|}$.

S-transform marginalization and inversion formula 2/2

Marginalization with respect to time

$$\int_{-\infty}^{+\infty} ST_x^{g}(t,\omega) dt = \iint_{\mathbb{R}^2} F_x(\omega+\Omega) F_h\left(\frac{\omega_0}{\omega}\Omega\right)^* e^{j\Omega t} \frac{d\Omega}{2\pi} dt \qquad (14)$$
$$= \int_{\mathbb{R}} F_x(\omega+\Omega) F_h\left(\frac{\omega_0}{\omega}\Omega\right)^* \delta(\Omega) d\Omega \qquad (15)$$
$$= F_x(\omega) F_h(0)^* \qquad (16)$$

Eq.(16) is equal to $F_x(\omega)$ when a Gaussian window is used (*i.e.* $F_h(0) = 1$).

Hence, \boldsymbol{x} can finally be reconstructed by applying the inverse Fourier transform which leads us to:

$$x(t) = \frac{1}{2\pi} \iint_{\mathbb{R}^2} \mathsf{ST}^{\mathsf{g}}_{\mathsf{x}}(\tau, \omega) \, \mathsf{e}^{j\omega t} \, d\tau d\omega \tag{17}$$

Time-Frequency Representations comparison

Comparison of the TFRs provided by S-transform, the STFT, and the Morlet CWT, applied to the Livingston GW150914 signal [Fourer et al., 2017].



Reassignment method [Kodera et al., 1978] [Auger & Flandrin 1995]

Principle

Improving the energy concentration (readability) of any bilinear distribution by reassigning its energy to new locations closer to real signal support. Consider the TFR of a signal x expressed in terms of the Wigner-Ville distribution as: $TFR_x(t,\omega) = \iint_{\mathbb{R}^2} WV_x(\tau,\Omega) \Phi(t-\tau,\omega-\Omega) d\tau d\Omega$

Method description

• Computation of the reassignment operators:

$$\hat{\mathbf{t}}(\mathbf{t},\omega) = \frac{\int_{\mathbb{R}^2} \tau \mathbf{W} \mathbf{V}_{\mathbf{x}}(\tau,\Omega) \Phi(\mathbf{t}-\tau,\omega-\Omega) d\tau d\Omega}{\int_{\mathbb{R}^2} \mathbf{W} \mathbf{V}_{\mathbf{x}}(\tau,\Omega) \Phi(\mathbf{t}-\tau,\omega-\Omega) d\tau d\Omega}$$
(18)

$$\hat{\omega}(\mathbf{t},\omega) = \frac{\int_{\mathbb{R}^2} \Omega W \mathbf{V}_{\mathbf{X}}(\tau,\Omega) \Phi(\mathbf{t}-\tau,\omega-\Omega) d\tau d\Omega}{\int_{\mathbb{R}^2} W \mathbf{V}_{\mathbf{X}}(\tau,\Omega) \Phi(\mathbf{t}-\tau,\omega-\Omega) d\tau d\Omega}.$$
(19)

Computation of the reassigned time-frequency representation:

$$\mathsf{RTFR}_{\mathbf{x}}(\mathbf{t},\,\omega) = \int_{\mathbb{R}^2} \mathsf{TFR}_{\mathbf{x}}(\tau,\,\Omega) \delta(\mathbf{t} - \hat{\mathbf{t}}(\tau,\,\Omega)) \delta(\omega - \hat{\omega}(\tau,\,\Omega)) \, \boldsymbol{d}\tau \, \boldsymbol{d}\Omega \tag{20}$$

The resulting reassigned TFR is a sharpened but non-reversible TFR, due to the loss of the phase information.

Reassignment and synchrosqueezing Second-order time-reassigned synchrosqueezed S-transform

The reassigned Stockwellogram

Reassignment operators

The reassignment operators can be reworded using S-transforms with modified analysis window (cf. [Fourer, Auger, hal-01467244, 2015] for the detailed proof):

$$\widetilde{t}_{x}(t,\omega) = t - \frac{\mathsf{ST}_{x}^{\mathcal{T}_{g}}(t,\omega)}{\mathsf{ST}_{x}^{g}(t,\omega)}, \qquad \qquad \widetilde{\omega}_{x}(t,\omega) = j\omega + \frac{\mathsf{ST}_{x}^{\mathcal{D}_{g}}(t,\omega)}{\mathsf{ST}_{x}^{g}(t,\omega)}, \qquad (21)$$

$$\widetilde{t}_{x}(t,\omega) = \mathsf{Re}(\widetilde{t}_{x}(t,\omega)), \qquad \qquad \widetilde{\omega}_{x}(t,\omega) = \mathsf{Im}(\widetilde{\omega}_{x}(t,\omega)) \qquad (22)$$

with $\mathcal{T}g(t) = tg(t)$ and $\mathcal{D}g(t) = \frac{dg}{dt}(t)$.

Reassignment

The reassigned Stockwellogram is finally computed as:

$$\mathsf{R}_{x}(t,\omega) = \iint_{\mathbb{R}^{2}} |\mathsf{ST}_{x}^{g}(\tau,\Omega)|^{2} \,\delta\left(t - \hat{t}_{x}(\tau,\Omega)\right) \delta\left(\omega - \hat{\omega}_{x}(\tau,\Omega)\right) d\tau \,d\Omega.$$
(23)

Reassignment and synchrosqueezing Second-order time-reassigned synchrosqueezed S-transform

Synchrosqueezing [Daubechies and Maes, 1996, 2011] [Thakur 2011]

Principle

- A particular reassignment method which allows to compute sharpen and reversible TFRs by moving the transform instead of its energy.
- Allows mode extraction by a ridge detection and local region integration procedure.

Synchrosqueezed S-transform (frequency-reassigned) [Fourer, Auger et al. 2015]

Based on the marginalization respect to frequency given by Eq. (12).

• Synchrosqueezed S-transform:

$$SST_{x}(t,\omega) = |\omega| \int_{\mathbb{R}} ST_{x}(t,\omega') \, \mathbf{e}^{j\omega't} \delta\left(\omega - \hat{\omega}(t,\omega')\right) \frac{d\omega'}{|\omega'|}, \tag{24}$$

• Reconstruction formula:

$$\hat{x}(t) = \frac{1}{C_h(\omega_0 T)} \int_{\mathbb{R}} SST_x(t, \omega) \frac{d\omega}{|\omega|},$$
(25)

Time-reassigned S-transform

Principle

- A new S-transform synchrosqueezing method based on the marginalization with respect to time given by Eq. (16).
- Inprovement of the readability of impulsive and strongly frequency-modulated component using an enhanced group-delay estimator.

Time-reassigned Synchrosqueezed S-transform

$$S_{x}^{g}(t,\omega) = \int_{\mathbb{R}} \mathsf{ST}_{x}^{g}(\tau,\omega) \,\delta\left(t - \hat{t}_{x}(\tau,\omega)\right) d\tau. \tag{26}$$

Signal Reconstruction

$$\int_{\mathbb{R}} S_{x}^{g}(t,\omega) dt = \iint_{\mathbb{R}^{2}} \operatorname{ST}_{x}^{g}(\tau,\omega) \delta\left(t - \hat{t}_{x}(\tau,\omega)\right) d\tau dt$$
(27)

$$= \int_{\mathbb{R}} \mathsf{ST}_{\mathsf{x}}^{\mathsf{g}}(\tau, \omega) d\tau = F_{\mathsf{x}}(\omega)$$
(28)

Hence, we obtain the exact reconstruction formula:

$$\hat{x}(t) = \iint_{\mathbb{R}^2} S_x^{g}(\tau, \omega) \, \mathbf{e}^{j\omega t} \, d\tau \frac{d\omega}{2\pi}$$
⁽²⁹⁾

Reassignment and synchrosqueezing Second-order time-reassigned synchrosqueezed S-transform

An enhanced Second-Order group-delay estimator 1/2

AM/FM signal model

$$x(t) = \mathbf{e}^{\lambda_{\mathbf{x}}(t) + j\phi_{\mathbf{x}}(t)}$$
(30)

with
$$\lambda_x(t) = l_x + \mu_x t + \nu_x \frac{t^2}{2}$$
 (31)

and
$$\phi_x(t) = \varphi_x + \omega_x t + \alpha_x \frac{t^2}{2}$$
 (32)

where $\lambda_x(t)$ and $\phi_x(t)$ are respectively the log-amplitude and the phase. This signal verifies $\frac{dx}{dt}(t) = (q_x t + p_x)x(t)$ with $q_x = \nu_x + j\alpha_x$, $p_x = \mu_x + j\omega_x$.

Properties

Differentiating with respect to t when $|ST_{x}^{g}(t,\omega)| > 0$, allows to compute: $\frac{\partial ST_{x}^{g}}{\partial t}(t,\omega) = ST_{x}^{\mathcal{D}g}(t,\omega) = -j\omega ST_{x}^{g}(t,\omega) + (p_{x} + q_{x}t)ST_{x}^{g}(t,\omega) - q_{x}ST_{x}^{\mathcal{T}g}(t,\omega)$ Hence, $\frac{ST_{x}^{\mathcal{D}g}(t,\omega)}{ST_{x}^{g}(t,\omega)} = p_{x} - j\omega + q_{x}\left(t - \frac{ST_{x}^{\mathcal{T}g}(t,\omega)}{ST_{x}^{g}(t,\omega)}\right)$ (33) and finally: $\widetilde{\omega}_{x}(t,\omega) = p_{x} + q_{x}\widetilde{t}_{x}(t,\omega)$

Reassignment and synchrosqueezing Second-order time-reassigned synchrosqueezed S-transform

An enhanced Second-Order group-delay estimator 2/2

$$t_{x}^{(2)} = \frac{\omega - \omega_{x}}{\alpha_{x}} = \hat{t}_{x}(t,\omega) + \frac{\omega - \hat{\omega}_{x}(t,\omega)}{\alpha_{x}} + \frac{\nu_{x}}{\alpha_{x}} \text{Im}(\tilde{t}_{x}(t,\omega))$$
(34)

which can be estimated by:

$$\hat{t}_{x}^{(2)}(t,\omega) = \begin{cases} \frac{\omega - \hat{\omega}_{x}(t,\omega) + \operatorname{Im}(\hat{q}_{x}(t,\omega) \ \tilde{t}_{x}(t,\omega))}{\operatorname{Im}(\hat{q}_{x}(t,\omega))} & \text{if } \operatorname{Im}(\hat{q}_{x}(t,\omega)) \neq 0\\ \hat{t}_{x}(t,\omega) & \text{otherwise} \end{cases}$$
(35)

where $\hat{q}_{x(t,\omega)}$ can be computed as [Fourer, Auger et al., 2015]:

$$\hat{q}_{x}(t,\omega) = \frac{(\mathsf{ST}_{x}^{\mathcal{Dg}}(t,\omega))^{2} - \mathsf{ST}_{x}^{\mathcal{D}^{2}g}(t,\omega)\mathsf{ST}_{x}^{g}(t,\omega)}{\mathsf{ST}_{x}^{\mathcal{T}\mathcal{D}g}(t,\omega)\mathsf{ST}_{x}^{g}(t,\omega) - \mathsf{ST}_{x}^{\mathcal{T}^{g}}(t,\omega)\mathsf{ST}_{x}^{\mathcal{D}g}(t,\omega)}$$
(36)

with $\mathcal{D}^2 g(t, T) = \frac{d^2 g}{dt}(t, T)$ and $\mathcal{T} \mathcal{D} g(t, T) = t \frac{dg}{dt}(t, T)$.

Reassignment and synchrosqueezing Second-order time-reassigned synchrosqueezed S-transform

Second-order horizontal synchrosqueezed S-transform

Principle

Consists in moving $ST_x^g(t,\omega)$ from the point (t,ω) to the point $(t_x^{(2)},\omega)$ such that $\frac{d\phi_x}{dt}(t_x^{(2)}) = \omega_x + \alpha_x t_x^{(2)} = \omega$.

Second-order horizontal synchrosqueezed S-transform is obtained by replacing \hat{t}_x by the second-order enhanced group-delay estimator $\hat{t}_x^{(2)}$.

Second-order horizontal synchrosqueezed S-transform

$$S_{x}^{g(2)}(t,\omega) = \int_{\mathbb{R}} \mathsf{ST}_{x}^{g}(\tau,\omega) \ \delta\left(t - \hat{t}_{x}^{(2)}(\tau,\omega)\right) d\tau. \tag{37}$$

Signal Reconstruction

The same reconstruction formula used by the (first-order) time-reassigned synchrosqueezed S-transform:

$$\hat{x}(t) = \iint_{\mathbb{R}^2} S_x^{g(2)}(\tau, \omega) \, \mathbf{e}^{j\omega t} \, d\tau \frac{d\omega}{2\pi}$$
(38)

Implementation consideration

Discretization

Computations are based on the rectangular approximation method and a uniform sampling approximation: $ST_x^g[k, m] \approx ST_x^g(\frac{k}{E_*}, 2\pi \frac{mF_g}{M}), F_s$ being the sampling frequency.

 $k \in \mathbb{Z}$ is the time sample index and $m \in \mathcal{M}$ is the discrete frequency bin. M is chosen as an even number: $\mathcal{M} = [-M/2 + 1; -1] \cup [1; M/2]$.

Gaussian window approximation

A threshold Γ is applied to obtain a finite number of time samples K_m at each time frame, when $\mathbf{e}^{-\frac{m^2(K_m/2)^2}{2(f_0 T)^2 M^2}} \leq \Gamma$:

$$\kappa_m \ge \frac{2Mf_0 T \sqrt{2\log(1/\Gamma)}}{|m|}.$$
(39)

with $\omega_0=2\pi f_0.$ In practice, we used $\Gamma=10^{-4}$ which provides good results with a reasonable computation time.

Time-frequency representations Signal reconstruction

TFRs comparison (RE=Rényi Entropy at order $\alpha = 3$)



18/20

Time-frequency representations Signal reconstruction

Signal reconstruction quality comparison

Reconstruction quality factor

$$\mathsf{RQF}(x, \hat{x}) = 10 \log_{10} \left(\frac{\sum_{k} |x[k]|^2}{\sum_{k} |x[k] - \hat{x}[k]|^2} \right), \tag{40}$$

Table : Reconstruction quality of the S-transform, the first- and the second-order horizontal synchrosqueezed S-transforms with $f_0 T = 2$, *M* varying from 300 to 2000 (a) and Γ varying from 10^{-1} to 10^{-4} (b).

(a)	$\frac{M (\Gamma = 10^{-4})}{RQF (dB)}$	300 0.85	500 54.10	1000 60.12	2000 66.14
(b)	$\begin{array}{l} \Gamma \ (M = 500) \\ RQF \ (dB) \end{array}$	10 ⁻¹ 53.45	10 ⁻² 54.10	10 ⁻³ 54.10	10 ⁻⁴ 54.10

Contributions summary

Summary

- A new second-order horizontal synchrosqueezing method based on an enhanced group-delay estimator designed for the S-transform
- Efficient computation using an S-transform with specific analysis windows
- A preliminary comparative evaluation of the S-transform with the STFT-based second-order horizontal synchrosqueezing

Future work

- Consideration of new signal models (e.g. hyperbolic chirp, high-order polynomial phase, etc.)
- Real-world application scenarios involving signal components extraction

Matlab code freely available at: https://fourer.fr/sthsst/